### **Fundamentals Physics**

### **Eleventh Edition**

Halliday

## **Chapter 9**

Center of Mass and Linear Momentum





- Types of collisions:
- Elastic collisions:
  - Total kinetic energy is unchanged (conserved)
  - A useful approximation for common situations
  - In real collisions, some energy is always transferred
- Inelastic collisions: some energy is transferred
- Completely inelastic collisions:
  - The objects stick together
  - Greatest loss of kinetic energy

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# 9-6 Momentum and Kinetic Energy in Collisions (8 of 8)

### **Checkpoint 7**

Body 1 and body 2 are in a completely inelastic onedimensional collision. What is their final momentum if their initial momenta are, respectively, (a) 10 kg  $\cdot$  m/s and 0; (b) 10 kg  $\cdot$  m/s and 4 kg  $\cdot$  m/s; (c) 10 kg  $\cdot$  m/s and -4 kg  $\cdot$  m/s?

### Answer:

- (a) 10 kg m/s
- **(b)** 14 kg m/s
- (c) 6 kg m/s

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## 9-8 Collisions in Two Dimensions (1 of 4)

### Learning Objectives

- **9.34** For an isolated system in which a two-dimensional collision occurs, apply the conservation of momentum along each axis of a coordinate system to relate the momentum components along an axis before the collision to the momentum components along the same axis after the collision.
- **9.35** For an isolated system in which a two-dimensional elastic collision occurs, (a) apply the conservation of momentum along each axis to relate the momentum components along an axis before the collision to the momentum components along the same axis after the collision and (b) apply the conservation of total kinetic energy to relate the kinetic energies before and after the collision.



## **9-8 Collisions in Two Dimensions** (3 of 4)

• Along x:  $m_1 v_{1i} = m_1 v_{1f} \cos \theta_1 + m_2 v_{2f} \cos \theta_2$ , Equation (9-79) • Along y:  $0 = -m_1 v_{1f} \sin \theta_1 + m_2 v_{2f} \sin \theta_2$ . Equation (9-80) • Energy:  $\frac{1}{2} m_1 v_{1i}^2 = \frac{1}{2} m_1 v_{1f}^2 + \frac{1}{2} m_2 v_{2f}^2$  Equation (9-81) • These 3 equations for a stationary target have 7 unknowns (since  $v_{2i} = 0$ ) : if we know 4 of them we can solve for the remaining ones.







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# 9-9 Systems with Varying Mass: A Rocket (4 of 7)

• From the equation:

$$-dMv_{rel} = Mdv$$

• We rewrite it as

$$dv = -v_{rel}\frac{dM}{M}$$

• Upon integrating we obtain a relation for the increase in the speed of the rocket during the change in mass from  $M_i$  to  $M_f$ , known as the second rocket equation:

$$v_f - v_i = v_{rel} \ln \frac{M_i}{M_f}$$
 Equation (9-88)

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# 9-9 Systems with Varying Mass: A Rocket (5 of 7)

### Rocket engine, thrust, acceleration

In all previous examples in this chapter, the mass of a system is constant (fixed as a certain number). Here is an example of a system (a rocket) that is losing mass. A rocket whose initial mass  $M_i$  is 850 kg consumes fuel at the rate R = 2.3 kg/s. The speed  $v_{rel}$  of the exhaust gases relative to the rocket engine is 2800 m/s. What thrust does the rocket engine provide?

Calculation: Here we find

 $T = Rv_{\rm rel} = (2.3 \text{ kg/s})(2800 \text{ m/s})$ 

 $= 6440 \text{ N} \approx 6400 \text{ N}.$ 

(Answer)

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# 9-9 Systems with Varying Mass: A Rocket (7 of 7)

### Rocket engine, thrust, acceleration

To be launched from Earth's surface, a rocket must have an initial acceleration greater than g = 9.8 m/s<sup>2</sup>. That is, it must be greater than the gravitational acceleration at the surface. Put another way, the thrust *T* of the rocket engine must exceed the initial gravitational force on the rocket, which here has the magnitude  $M_{ig}$ , which gives us

 $(850 \text{ kg})(9.8 \text{ m/s}^2) = 8330 \text{ N}.$ 

Because the acceleration or thrust requirement is not met (here T = 6400 N), our rocket could not be launched from Earth's surface by itself; it would require another, more powerful, rocket.





<b>9 Summary</b> (3 of 5)	
Inelastic Collision in 1D	
<ul> <li>Momentum conserved along that dimension</li> </ul>	
$m_1 v_{1i} + m_2 v_{2i} = m_1 v_{1f} + m_2 v_{2f}.$	Equation (9-51)
Motion of the Center of Mass	
<ul> <li>Unaffected by collisions/internal forces</li> </ul>	
<b>Collisions in Two Dimensions</b>	
• Apply conservation of momentum along each individually	axis
• Conserve <i>K</i> if elastic	
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